

## UK Royal Navy Supports Trials of Underwater Micro-robots





An innovative marine robot, called ecoSUB, has been successfully trialled off the Orkney Isles in northern Scotland during a marine robot demonstrator mission coordinated by the National Oceanography Centre (NOC). The ecoSUBs are a new type of Autonomous Underwater Vehicle (AUV) developed by Planet Ocean in partnership with the NOC. The vehicles are less than one

metre in length and weigh only 4kg, and are therefore called 'micro-AUVs'. Despite their small size, they are capable of diving to 500m and have sufficient battery power to stay underwater for several hours.

Two of the ecoSUB vehicles were deployed from the Royal Navy's *HMS Enterprise* during the latest Marine Autonomous Systems in Support of Marine Observations (MASSMO) trial. The ecoSUBs successfully collected oceanographic data to depths of 100m, and this data will be compared with those collected by traditional 'over-the-side' instruments deployed from the ship, allowing the Royal Navy and the <u>Defence Science and Technology Laboratory</u> (Dstl) to assess the benefits of this new robotic technology.

## Paving the way

A Dstl spokesperson said "The development, de-risking and demonstration of new technologies for the Royal Navy is a key requirement for Dstl. The MASSMO missions have proven to be very successful in understanding the capability of marine autonomous systems and paving the way for their transition into the Royal Navy. The recent use of ecoSUBs from *HMS Enterprise* has demonstrated their practicality of deployment and recovery, with the upcoming analysis of the data they provide determining their value in an operational context."



Two of the new ecoSUB vehicles were deployed from the Royal Navy's HMS Enterprise during the latest Marine Autonomous Systems in Support of Marine Observations (MASSMO) trial.

A Royal Navy spokesperson said "The MASSMO missions have been a great success in helping the Royal Navy better understand how to deploy and operate marine autonomous systems to achieve good quality data. We were very pleased that *HMS Enterprise* could assist the mission, both in the launch and recovery of ecoSUBs and collection of data using the ships' own equipment. We look forward to the analysis of oceanographic data and the comparison of ship and marine autonomous system datasets."

## Transforming data collection across the maritime sector

Terry Sloane, managing director of Planet Ocean, said "Micro-AUVs are low cost and highly flexible platforms with the potential to transform data collection across the maritime sector. This demonstrator mission provided a fantastic opportunity for us to deploy ecoSUBs from a Royal Navy vessel in challenging conditions, and we are delighted at the quality of data obtained and the ease with which the vehicles were released and recovered."

In addition to the ecoSUBs, the mission successfully deployed two submarine gliders operated by the Marine Autonomous and Robotic Systems facility at the NOC. These gliders were carrying acoustic monitoring devices provided by the University of East Anglia and RS Aqua, capable of recording vocalising marine mammals and man-made noises in the survey area up to 100km offshore in the northern North Sea.

## **Autonomous technologies**

The marine robot fleet targeted oceanographic features identified on satellite images provided by Plymouth Marine Laboratory, and surfaced every few hours to transmit oceanographic data back to the NOC via satellite; this data was then passed to the Met Office and Royal Navy to test how the data can improve operational forecasting.

The mission also provided an opportunity for the NOC, the Scottish Association for Marine Science (SAMS) and the British Oceanographic Data Centre (BODC, also part of NOC) to test new developments in marine robot 'command-and-control', and to showcase a new visualisation suite where incoming data could be viewed and analysed; these developments contribute to the <u>Oceanids marine robot development programme</u>, which is part of the UK Government's <u>Industrial Strategy Challenge Fund</u>.



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Prof Russell Wynn of the NOC, and Chief Scientist of the mission, said "For the last five years, we have run annual MASSMO missions in some of the UK's toughest offshore environments, highlighting the strengths and weaknesses of new autonomous technologies. These missions also highlight the innovative approach taken by the NOC towards technology development, industry partnerships, and advice to UK Government. We are now hoping to run similar missions in the Arctic, with the aim of sending the next generation of marine robots under the ice to measure this rapidly changing environment."

https://www.hydro-international.com/content/news/uk-royal-navy-supports-trials-of-underwater-micro-robots